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RDTE PROJECT NO. 1X141807D174 USAAVCOM PROJECT NO. USAAVNTA PROJECT NO. 66-06



## FEASIBILITY TEST OF TRACTOR TAIL ROTOR MODIFICATION ON THE AH-1G HELICOPTER

#### FINAL REPORT

JOHN R. MELTON PROJECT ENGINEER

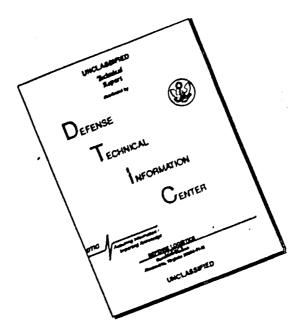
GARY C. HALL MAJOR, TC US ARMY PROJECT PILOT

**MARCH 1968** 

US ARMY AVIATION TEST ACTIVITY
EDWARDS AIR FORCE BASE, CALIFORNIA 93523

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SAVTE P

30 April 1968

SUBJECT: Change No. 1 to Final Report for Feasibility Test of Tractor Tail Rotor Modification on the AH-1G Helicopter, USAAVNTA Project No. 66-00

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The following changes are made to subject final report:

- a. Page ii, reverse of front cover, change AMCPM-LH to read AMCPM-IR in lines 5, 5, 22.
- b. Document Control Date R&D, DD Form 1473 following page 72 change:
- (1) Item 19, change Hq, US Army Aviation Materiel Command, Attn: AMSAV-0, P. 0. Box 205, Main Office, St Louis, Missouri 63166 to read Hq, US Army Materiel Command, Attn: AMCPM-IR, Washington, D. C. 20315.
- (2) Item 12, change Commanding General, US Army Aviation Materiel Command ATTN: AMSAV-0, P. 0. Box 200, Main Office, St. Louis, Missouri 63166 to read Hq, US Army Materiel Command, Attn: AMCPM-IR, Washington, D. C. 20315.

FOR THE COMMANDER:

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FRANK A. LEAVENS

CPT, AGC Adjutant )\_\_\_\_\_

RDTE PROJECT NO. 1X1418D174 USAAVCOM PROJECT NO. USAAVNTA PROJECT NO. 66-06

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#### **ABSTRACT**

A feasibility test of the tractor tail rotor modification of the AH-1G helicopter was conducted near Fort Worth, Texas (550feet elevation), and Alamosa, Colorado (7535-feet elevation), during the period 7 October to 19 October 1967. This test was conducted to obtain quantitative flight test data to serve as a basis for determining if the tractor tail rotor modification proposed by the contractor for the AH-1G helicopter would correct the directional control problems which currently exist on the AH-1G helicopter with the standard tail rotor configuration. This test revealed that in-ground-effect (IGE) low speed directional control and IGE low speed dynamic directional stability were greatly improved by installation of the tractor tail rotor. IGE directional control limitations with the standard tail rotor installed were encountered at approximately 8100 pounds gross weight near sea level in previous tests. This test with the tractor tail rotor did not reveal any IGE directional control limitations at approximately 8940 pounds gross weight and near sea level. The test results indicate that additional directional control could be obtained with the tractor tail rotor, if the geometry of the directional control system were changed to negate the adverse effects of the stability and control augmentation system (SCAS) on the ability to obtain full left tail rotor pitch. The highest tail rotor horsepower encountered with large left pedal inputs to arrest hovering turns was 250 shaft horsepower. These tests proved that directional control deteriorated with increased gross weight, increased density altitude or decreased rotor speed. The test aircraft exhibited SCAS coupled pylon motion which has been a continuing problem on the AH-1G helicopter.

#### **FOREWORD**

During the conduct of the feasibility test of the tractor tail rotor both at Fort Worth, Texas, and Alamosa, Colorado, the helicopter and special test instrumentation were maintained under contract by Bell Helicopter Company personnel. At Fort Worth, Texas, the City of Grand Prairie, Texas, provided the test site at Grand Prairie Municipal Airport. At Alamosa, Colorado, the city of Alamosa provided the test site at Alamosa Municipal Airport. The Alamosa Volunteer Fire Department provided fire fighting equipment and personnel.

### TABLE OF CONTENTS

																				Page
INTRODU	CTION																			
Backg: Test Descri Scope Method Chrone	Objectiption of Teds of	tive n . est Test		•	•			•	•		:			 •	•				•	1 2 2 3 4 4
Paced Hover Arres SCAS	Fligh	nt . n Win of '	nds Tur	n	Ra			•	•	•	•	•			•		•			5 7 8 8
CONCLUS	IONS	<b>.</b> .											•	•	•					9
RECOMME	NDATI	ONS	•			•	•	•			-			•						10
APPENDI.	XES																			
IV.	Test AH-10	Data Ins G Ope	a tru era	me	ent	at	ii Lir	on nit	·	tio	· ons	•	•	•	•	•	•	•	•	67 68
V.	Dist	ribu	tio	n			_				_									70

#### INTRODUCTION

#### BACKGROUND

1. During tests conducted by the US Army Aviation Test Activity (USAAVNTA) on AH-1G helicopter S/N 66-15246 in April 1967 (ref 2, app I), it was determined that the directional control power was inadequate at some conditions within the contractor's proposed flight envelope. That test was conducted with a 20-degree tail rotor rigging. The contractor rerigged the tail rotor to 23 degrees, as a result of these findings, in an attempt to solve the directional control power problem. During tests in the 23-degree rigging configuration, the contractor encountered high power loads in the tail rotor drive train when full left directional control inputs were required. The high power loads (290 horsepower) caused considerable damage to the 42-degree and 90-degree gear boxes. The output gear train from the main transmission to the tail rotor drive was also damaged. Replacement of these components was required. Later, in an attempt to solve the problem by use of a reconfigured tail rotor blade, the same phenomenon was experienced with 270-peak horsepower to the tail rotor. This necessitated replacement of the three gear boxes again. The maximum continuous operation design point for the tail rotor is 120 horsepower. At this point the contractor determined that the maximum allowable left pedal tail rotor rigging was 19 degrees due to the tail rotor drive train power loading problem. The contractor stated that approximately 230 horsepower was the maximum attainable with a 19-degree tail rotor rigging. While pursuing a permanent solution to this problem on another test helicopter, the contractor was directed to determine the inground-effect (IGE) flight envelope at the 19-degree tail rotor rigging with AH-1G helicopter S/N 66-15248 for gross weights of 7500, 8500, and 9500 pounds (ref 3, app I). At the completion of this contractor test, USAAVNTA was directed by, US Army Aviation Materiel Command (USAAVCOM) to determine the areas of inadequate directional control power for 8100 pounds gross weight with a center of gravity of 194.5 inches. That test proved that there were areas of inadequate directional control at 8100 pounds, the lowest practical mission weight (ref 4 and 5, app I). As a result of these tests, various warnings and flight restrictions were imposed on the AH-1G helicopter. Since these restrictions were undesirable and the high horsepowers being experienced by the tail rotor drive train were not desirable, the contractor continued to pursue a solution. The contractor proposed that a tractor type tail rotor, described in reference 6, appendix I, be installed on the AH-IG helicopter to alleviate the problem. Limited flight tests by the contractor were conducted near sea

level and at a high altitude test site. These tests proved to the contractor's satisfaction that the tractor tail rotor configuration was the optimum long range solution to the problem and led to the submission of Engineering Change Proposal AH-1G 350, Tractor Tail Rotor (ref 6, app I). On 25 September 1967, USAAVCOM directed that USAAVNTA conduct an evaluation of the tractor tail rotor (ref 7, app I). The test sites selected for these tests were Fort Worth, Texas (550-reet elevation) and Alamosa, Colorado (7535-feet elevation).

#### TEST OBJECTIVES

- 2. To provide quantitative flight test data to serve as a basis for determining if the tractor tail rotor modification proposed by the contractor for the Ali-IG helicopter will correct the directional control problem defined in reference 2 through 5, appendix I.
- 3. To provide quantitative flight test data to serve as a basis for determining if Bell Helicopter Company Engineering Change Proposal AH-1G 350 should be approved.

#### DESCRIPTION

4. The test aircraft is the second prototype AH-1G tactical helicopter produced by Bell Helicopter Company designed specifically for the armed role. It is a tandem, two-place, high speed conventional helicopter with a two-bladed door hinge type main rotor and prototype antitorque rotor. The prototype tail rotor is located on the right side of the tail boom instead of the standard left side location. The prototype is similar to that proposed in reference 6, appendix I. The tail rotor blades are standard and set at the standard 19-degree rigging for full left pedal. A three-axis stability and control augmentation system (SCAS) is used in lieu of the stabilizer bar to improve helicopter stability and handling qualities. The test helicopter is powered by a Lycoming T53L-13 turboshaft engine rated at 1400 shaft horsepower (shp) at sea level (S.L.) standard day conditions. The power plant is derated to 1100 shp at 314 rotor rpm due to maximum torque limits of the helicopter main transmission. The distinctive features of the test helicopter are the 36-inch wide fuselage, the stub mid-wings with four external stores stations, and the integral chin turret. The armament configuration of the AH-1G is changed by varying wing stores. The flight control system is a positive mechanical type with conventional helicopter controls in the pilot's aft cockpit. The copilot/gunner's forward cockpit is provided with sidearm collective and cyclic controls. Control forces are reduced by hydraulic servo cylinders connected to the control

system mechanical linkage and powered by dual transmission driven pumps. A synchronized elevator is used to increase static longitudinal stability and lengthen the center of gravity (C.G.) range. A force trim system is provided in the control system to give artificial control feel and positive control centering. Ausform Armor protection is provided for the crew, engine fuel control, and engine compressor section.

#### SCOPE OF TEST

- 5. The scope of this test conducted on AH-IG helicopter S/N 66-15246 at Grand Prairie Municipal Airport near Fort Worth, Texas, and Alamosa Municipal Airport, Colorado, was limited entirely to directional control testing during IGE flight. The reason for this limited scope of test was that the tractor tail rotor is a prototype system and has not been tested by the contractor throughout the flight envelope.
- 6. The flight restrictions which governed this test are presented in appendix IV. A safety of flight release for these flight restrictions was issued by USAAVCOM (ref 8, app I).
- 7. Eighteen flights were conducted during this test for a total of 12.4 test hours during an elapsed calendar time of 12 days.
- 8. Three types of tests were conducted: paced flight, hovering in winds, and arrestment of turn rates. The test conditions for these tests are listed in Table 1.

Table 1. Test Conditions.

	rabre	1. Test Conditions	•	
TYPE OF TL3T	AVG S WEIGHT (1b)	AVG DENSITY ALTITUDE (ft)	ROTOR SPEED (rpm)	CENTER OF GRAVITY (in.)
Paced F1/ght	8030	<b>73</b> 30	324	192.5
PaceJ Flight	8020	7790	7,4	192.5
Paced Flight	8680	7190	324	192.4
Paced Flight	8940	-150	324	193.5
Paced Flight	9510	-120	324	193.7
Hovering in wind	9130	<b>87</b> 60	324	192.5
Arrestmen of Turn R	9100	8750	324	192.5
Arrestmen of Turn R	8100	7920	324	192.7

#### METHODS OF TEST

- 9. The methods for the three tests conducted are described briefly below:
- a. Paced Flight: Paced IGE flight at various relative wind azimuths was conducted in light-steady winds (0 to 6 knots (kt)) using a calibrated pace car and wind speed and direction measuring devices in immediate proximity to the test site. Wind speed and direction were continuously and accurately recorded during all testing and correlated with each data point. A Very High Frequency (VHF) radio was installed in the test helicopter which netted with other VHF radios in the pace car and at the wind measuring site. This was necessary to correlate data points. Control positions, rates, attitudes, and tail rotor power were recorded on oscillograph at stabilized IGE flight speed increments up to the limit of control authority or 30 kt, whichever occurred first.
- b. Hovering in winds: Stabilized hovering over a spot was conducted at various wind azimuths and velocities. Control position requirements and tail rotor power were recorded as function of wind azimuth.
- c. Arrestment of Turn Rates: While hovering over a spot, right turn rates of various magnitudes were arrested at a selected helicopter heading with varying rates of pedal application. Pedal requirements and tail rotor power were recorded.

#### CHRONOLOGY

10. The chronology of this test program is as follows:

Test nelicopter received	/	Uctober	TAPA
Flight test commenced	7	October	1967
Flight test completed	19	October	1967
Test helicopter returned to			
contractor	19	October	1967
Draft test report submitted	31	October	1967
Final test report forwarded		March	1968

#### RESULTS AND DISCUSSION

#### PACED FLIGHT

- 11. Paced flight at selected relative wind azimuths was the primary technique used to produce the quantitative definition of the conditions of inadequate directional control. Figures 1 through 47, appendix II, present the results of these tests. The mean (average) directional control position for the condition and the maximum excursion toward full left directional control input for each data point were determined. The magnitude of the maximum excursion from the average is some indication of the degree of instability for the condition. Figures 1, 13, 24, 34, and 43, appendix II, summarize the conditions for inadequate directional control.
- 12. For the purposes of this test, directional control was determined to be inadequate where the maximum excursion of directional control extended to less than 12.5 percent of full travel. Depending upon the position of the SCAS actuator at any instant, the left directional control "stop" may vary from 0 percent to 12.5 percent of full SCAS off left tail rotor pitch. This can result in something less than the 19-degree full left tail rotor pitch setting when the pedal is on the "stop". With the directional control channel of the SCAS disengaged, full left tail rotor pitch is always available.
- 13. Figures 2 through 12, appendix II, present the results of the tests conducted at 8030 pounds average gross weight, 324 rotor rpm, and 7330 feet density altitude. Figure 1, appendix II, summarizes the conditions for inadequate directional control (shaded areas). This figure shows that directional control is inadequate for the conditions tested for air speeds greater than 14 kt true air speed at relative wind azimuths in right sideward flight of approximately 55 degrees to 125 degrees. These test conditions were the baseline conditions for the tests conducted at the high altitude test site. From this baseline, gross weight and rotor speed were varied to determine their affects on the areas of inadequate directional control.
- 14. Figures 14 through 23, appendix II, present the results of the tests conducted at 8020 pounds average gross weight, 314 rotor rpm, and 7790 feet density altitude. Figure 13, appendix II, summarizes the conditions for inadequate directional control (shaded areas).

This figure shows that directional control is inadequate in several areas for these test conditions. In right sideward flight directional control became inadequate at 8 kt. The critical speed increased to approximately 15 kt, 20 degrees to 30 degrees either side of straight right sideward flight. Two other small areas of inadequate directional control were detected in straight rearward flight and at the 230 degree to 270 degree relative wind azimuths from approximately 7-14 kt. Since all other parameters were the same as baseline (para 13) except rotor speed which was reduced to 314 rpm, it is concluded that reduced rotor speed had a significant adverse affect on directional control.

- 15. Figures 25 through 33, appendix II, present the results of the tests conducted at 8680 pounds average gross weight, 324 rotor rpm, and 7190 feet density altitude. Figure 24, appendix II, summarizes the conditions for inadequate directional control (shaded areas). This figure shows that directional control is inadequate in several areas for these test conditions. In right sideward flight the critical speed for inadequate directional control varied from approximately 14 kt in straight right sideward flight to approximately 8 kt at 110 degree relative wind azimuth. At relative wind azimuths from 150 to 180 degrees, a small area of inadequate directional control was noted from 6 kt to 12 kt. Since gross weight was the only parameter changed from the baseline conditions, it is apparent (comparing figure 24 with figure 2, appendix II) that an increase in gross weight adversely affects directional control.
- 16. Figures 35 through 42, appendix II, present the results of the tests conducted at 9510 pounds average gross weight, 324 rotor rpm, and -120 feet density altitude. Figure 34, appendix II, summarizes the conditions for inadequate directional control (shaded areas). This rigure shows that a small area of inadequate directional control exists in the right sideward flight between relative wind azimuths of approximately 65 degrees and 105 degrees and true airspeeds between 15 kt and 28 kt. The effects of density altitude on directional control are indicated by this test since only a small area of inadequate control existed at near sea level conditions at 9510 pounds gross weight whereas at 9130 pounds gross weight at the high altitude test site directional control was inadequate at practically all relative wind azimuths in winds from 0 kt to 8 kt as shown in figure 48, appendix II.
- 17. Figures 44 through 47 present the results of the tests conducted at 8940 pounds average gross weight, 324 rotor rpm, and -150 feet density altitude. Figure 43, appendix II, summarizes the conditions for inadequate directional control (shaded areas). No areas of inadequate directional control were detected for the conditions tested at any relative wind azimuth up to true airspeeds in excess of 30 kt.

- 18. The paced flight tests showed that reduced rotor speed, increased gross weight, and increased density altitude all adversely affect directional control. It is most significant that at 8010 pounds average gross weight at near sen level with the standard tail rotor, an area of inadequate directional control existed between relative wind azimuths of approximately 170 degrees and 250 degrees and true airspeed of 8 kt to 13.5 kt (para 22, ref 4, app I). At the same test site, with the tractor tail rotor, no areas of inadequate directional control exist at a gross weight of 8940 pounds. At near sea level density altitude 324 rpm, the gross weight for adequate directional control was raised from less than 8010 pounds to more than 8940 pounds with the installation of the tractor tail rotor. A comparison of the tractor tail rotor to the standard tail rotor at high density altitude was not possible due to insufficient standard tail rotor data. Density altitude, however, should have a similar adverse affect upon both the standard and tractor tail rotor. The improvement in directional control with the tractor tail rotor measured near sea level should exist at higher density altitudes.
- 19. A secondary effect contributing to the improvement of directional control with the tractor tail rotor was reduction of the magnitude and frequency of random external directional disturbances. With combinations of wind azimuth and velocity approaching areas of inadequate control, the standard tail rotor required rapid and sometimes large directional control excursions to maintain heading (ref 4, app I). With the tractor tail rotor, the directional disturbances were greatly reduced, and large excursions of directional control were not required.
- 20. Table 2 through 6, appendix II, present the peak tail rotor shaft horsepower obtained for each data point. These values are included on the figures of tail rotor pitch versus true airspeed.

#### HOVERING IN WINDS

- 21. Figure 48, appendix II, shows the tail rotor pitch required to hover at 9130 pounds g. s weight, 192.5 inch C.G., 324 rpm rotor speed, and 8760 feet density altitude. During this test the wind was variable in direction and velocity so that the accuracy of the wind azimuth data was compromised. However, as figure 48, appendix II, indicates, directional control was inadequate for most wind azimuths, including low wind velocities (less than 8 kt).
- 22. The test conditions of figure 48, appendix II, are well within the hover performance envelope of the directaft. This condition results in the hover ceiling of the helicopter being defined by

available directional control rather than engine power available. This also means that the hover ceiling of the helicopter will vary greatly with both wind velocity and azimuth.

#### ARRESTMENT OF TURN RATES

Figure 49, appendix II, shows the tail rotor shaft horsepower resulting from arresting right hovering turns. Peak horsepowers of approximately 250 shaft horsepower were recorded. These high horsepowers resulted in changes in the wear patterns on the tail rotor drive train gear boxes, but replacement was not required. Peak tail rotor shaft horsepower was found to be primarily a function of the total pedal displacement required to arrest the turn rate. Based upon the very limited amount of data available for analysis, the tail rotor power required to arrest a turn rate could not individually be defined in terms of yaw rate, yaw angular acceleration, or rate of pedal displacement. All these parameters undoubtedly affect the magnitude of the resulting tail rotor shaft horsepower, but their individual contributions could not be defined with the data available from these tests. However, there is sufficient information to show that the most significant parameter affecting peak tail rotor shaft horsepower is the size of the pedal displacement required to arrest the turn rate and not the rate of displacement. This indicates that the installation of a rate limiting device on the directional controls or the publishing of yaw rate limitations in the operator's manual is not appropriate. A note to avoid large pedal inputs which are not required in normal operation of the helicopter should be included in the pilot's handbook.

#### SCAS PYLON COUPLING

24. During this test program, while flying from the contractor's facility to the test site, SCAS coupled pylon motion was encountered. The severity of the oscillation was comparable to that reported in reference 4, appendix I. The test aircraft was equipped with the pylon position sensors designed to eliminate this continuing problem. Production AH-IG aircraft are presently delivered with essentially the same pylon position sensing equipment as that installed on the test aircraft.

#### CONCLUSIONS

- 25. Installation of the tractor tail rotor in the AH-IG helicopter results in greatly improved IGE, low speed directional control compared to the standard tail rotor (para 18).
- 26. The AH-1G helicopter with the tractor tail rotor installed has adequate directional control to hover in a 30-kt wind from any relative wind azimuth at a gross weight of 8940 pounds, density altitude of approximately sea level, and rotor speed of 324 rpm (para 17).
- 27. At a gross weight of 9510 pounds, density altitude of approximately sea level, and rotor speed of 324 rpm, inadequate directional control exists in the area of a right cross wind between relative wind azimuths of approximately 65 degrees and 105 degrees and wind velocities between 15 and 28 kt (para 16).
- 28. Directional control deteriorates with increased gross weight, increased density altitude, or decreased rotor speed (para 18).
- 29. The hover ceiling of the AH-1G is limited for some conditions by inadequate directional control rather than performance (para 22).
- 30. With the present directional control system geometry, it is possible to have the directional pedal fully to the left stop and not achieve maximum left tail rotor pitch. This results in a decrease in directional control available to the pilot at some conditions of SCAS actuator extension (para 12).
- 31. The magnitude and frequency of the random external directional distrubances observed with the standard tail rotor at combinations of wind velocity and relative wind azimuth approaching the limits of directional control are greatly reduced with the tractor tail rotor (para 19).
- 32. With large left pedal inputs to arrest a turn rate, peak tail rotor shaft horsepowers of approximately 250 shaft horsepower were recorded (para 23).
- 33. The test aircraft exhibited SCAS coupled pylon motion (para 24).

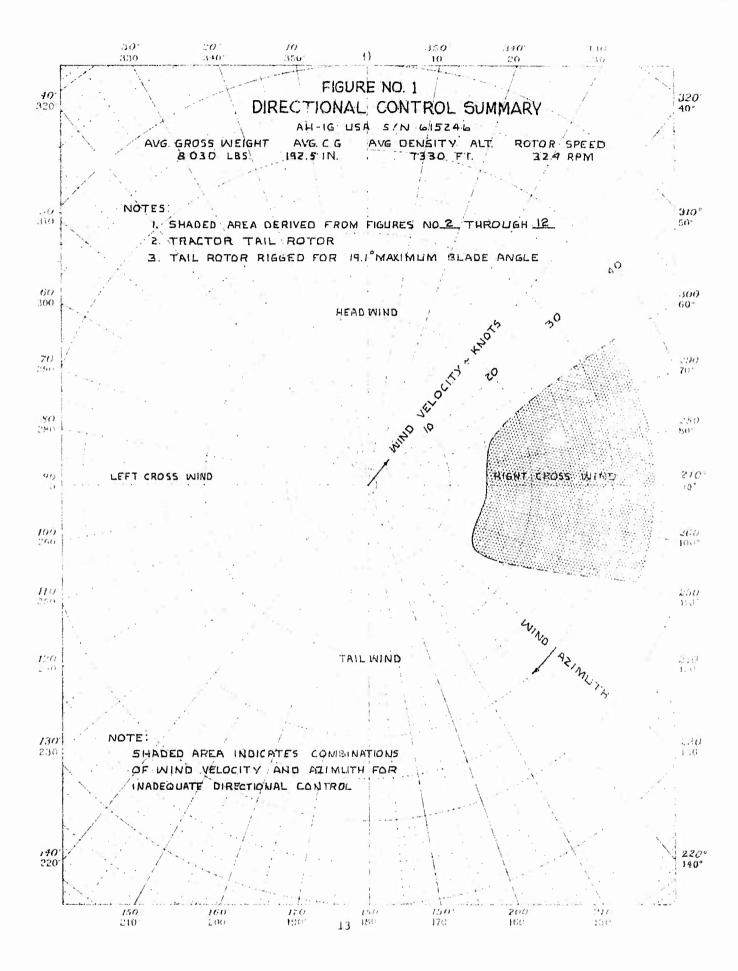
#### RECOMMENDATIONS

- 34. Further testing throughout the entire flight envelope should be conducted on the AH-IG helicopter in the tractor tail rotor configuration to insure that no penalties on performance, handling qualities, or structural integrity are suffered as a result of this modification. Particular attention should be focused on high speed maneuvering flight and those flight regimes which demand maximum right directional control requirements (para 5).
- 35. Consideration should be given to further improving the IGE low speed directional control power characteristics by a redesign of the directional control system geometry to allow the pilot to obtain full left tail rotor pitch with any SCAS actuator position (para 12).
- 36. If the tractor tail rotor is approved for production in the configuration tested, a note should be included in the pilot's handbook to disengage the directional SCAS channel if inadequate IGE directional control is encountered. This will allow the pilot to obtain full left tail rotor pitch with any SCAS actuator position (para 12).
- 37. Rotor speed should be maintained at 324 rpm during IGE flight (para 18).
- 38. Tests should be conducted to determine a final, adequate corrective measure to prevent SCAS coupled pylon motion (para 24).

#### APPENDIX I REFERENCES

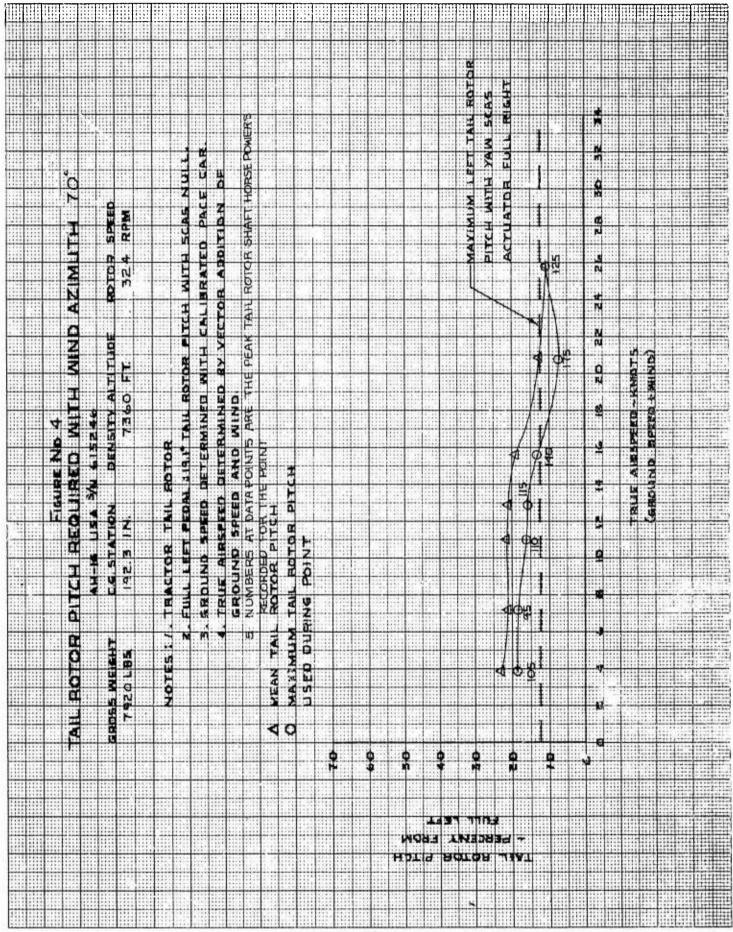
- 1. Preliminary Draft Letter Plan of Test for, "Feasibility Test of Tractor Tail Rotor Modification on the AH-1G Helicopter," 2 October 1967.
- 2. Preliminary Letter Report of Phase B, "Engineering Flight Test of AH-1G Helicopter/Hueycobra, S/N 66-15246," April 1967.
- 3. "Model 209 Controllability, Warning, Approach and Maneuver Envelope Documents," presented by Bell Helicopter Company on 28 July 1967.
- 4. Preliminary Draft Letter Report, "Engineering Flight Test of the AH-IG Helicopter to Determine the Area of Inadequate Directional Control Power at 8100 Pounds Gross Weight," 17 August 1967.
- 5. Letter from Cobra Test Team to Commanding Officer, USAAVNTA, subject: "Excessive Gear Box Wear at Standard 19-Degree Tail Rotor Rigging on AH-1G Helicopter," 10 August 1967.
- 6. Bell Helicopter Company, "Engineering Change Proposal AH-1G350, Improved Anti-Torque System for the AH-1G Helicopter," 29 August 1967.
- 7. Unclassified Message 9-1388 AMSAV-EF, CG, USAAVCOM to CO, USAAVNTA, Subject: "Evaluation of Tractor Tail Rotor AH-1G," 25 September 1967.
- 8. Unclassified Message 500-09-11 AMSAV-EF, CG, USAAVCOM to CO, USAAVNTA, subject: "Safety of Flight Release for USAAVNTA Test of Tractor Tail Rotor on AH-1G," 30 September 1967.

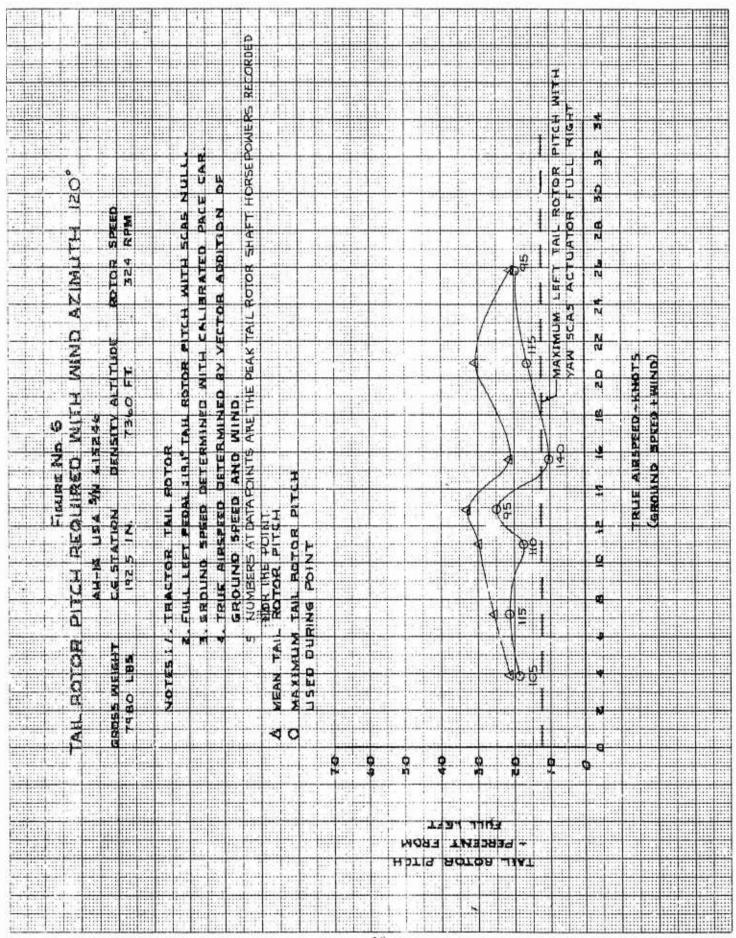
## APPENDIX II TEST DATA

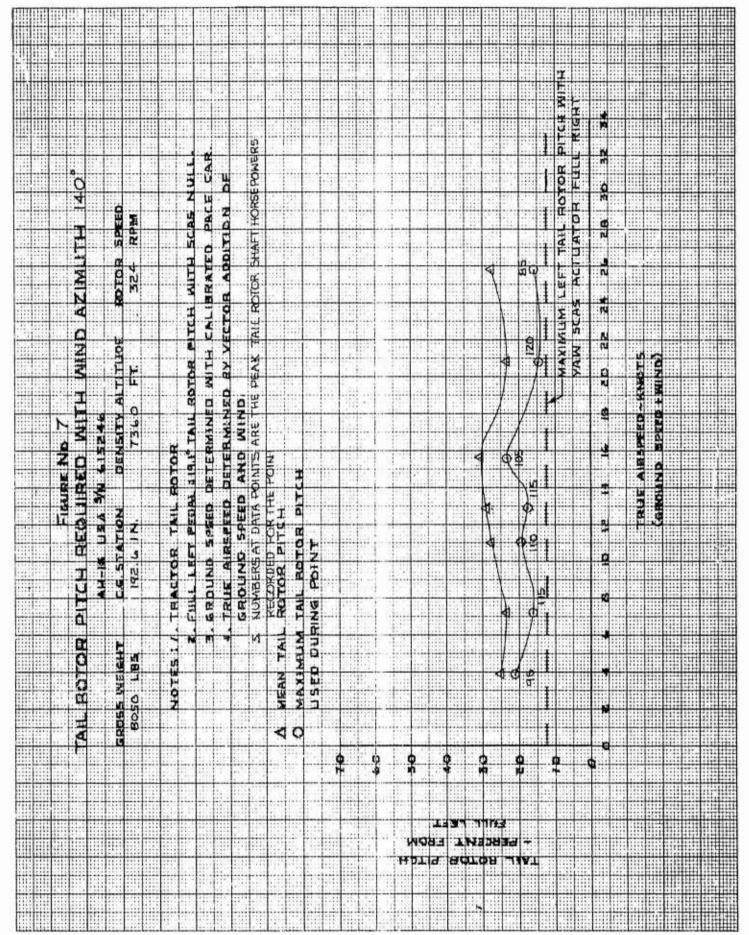


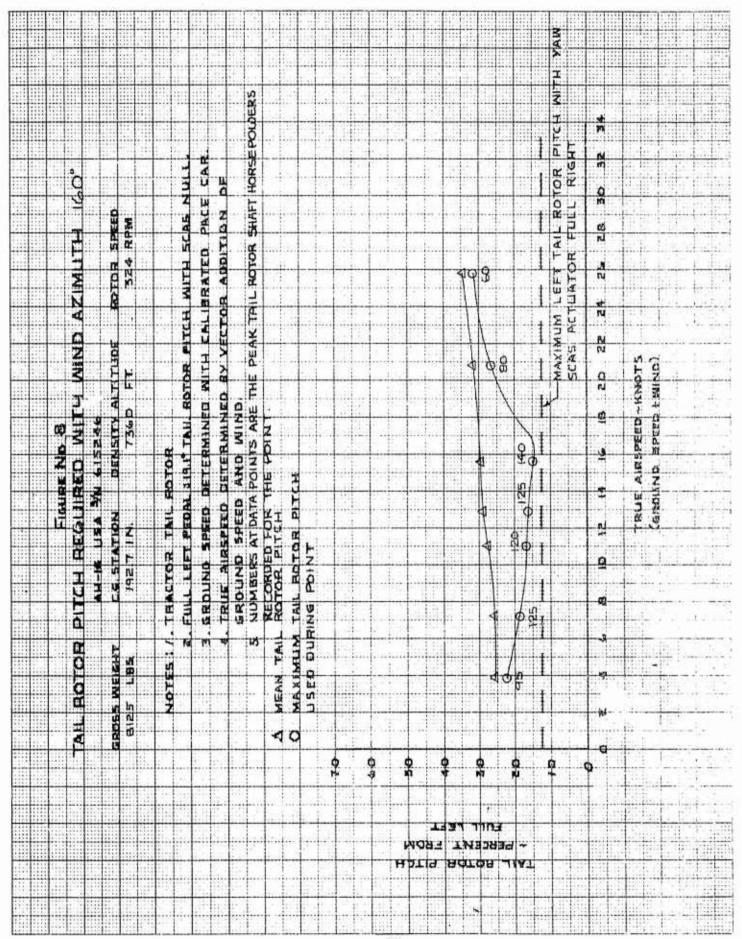
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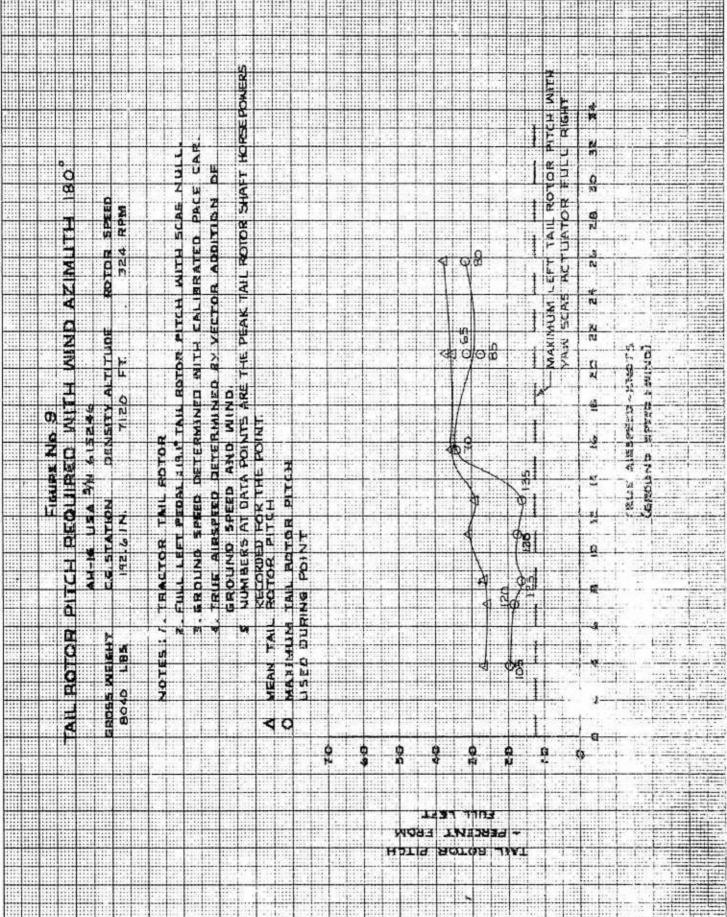
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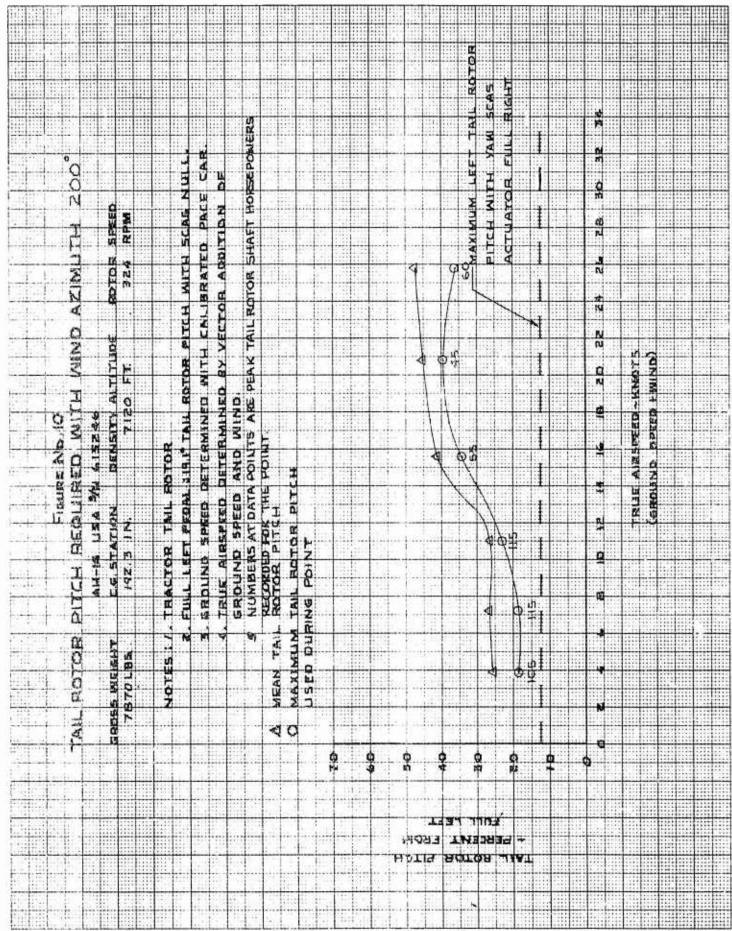


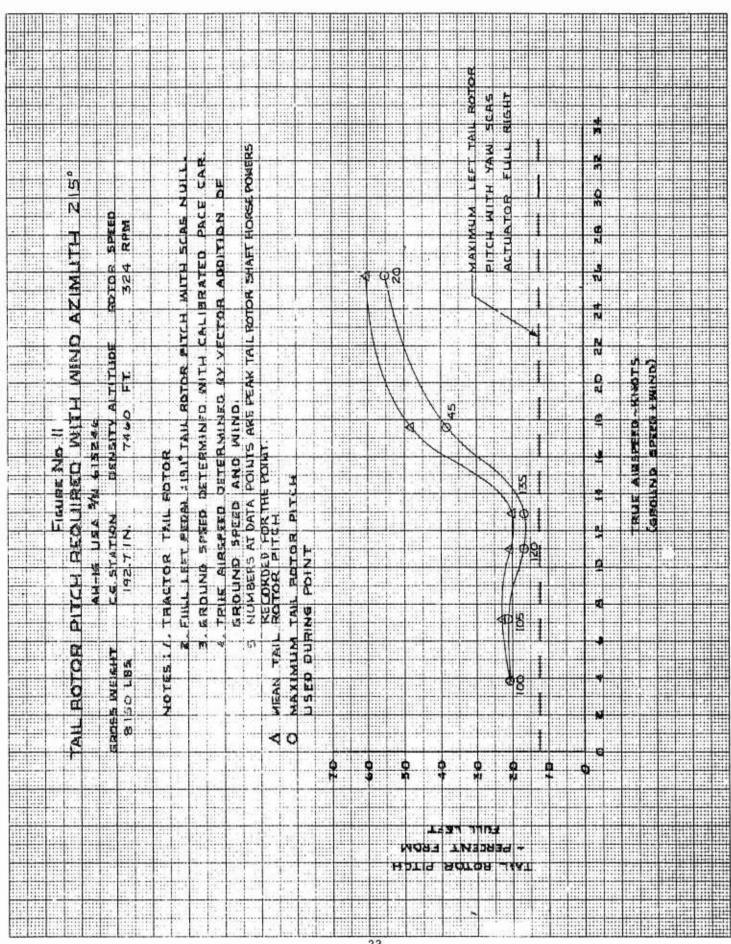


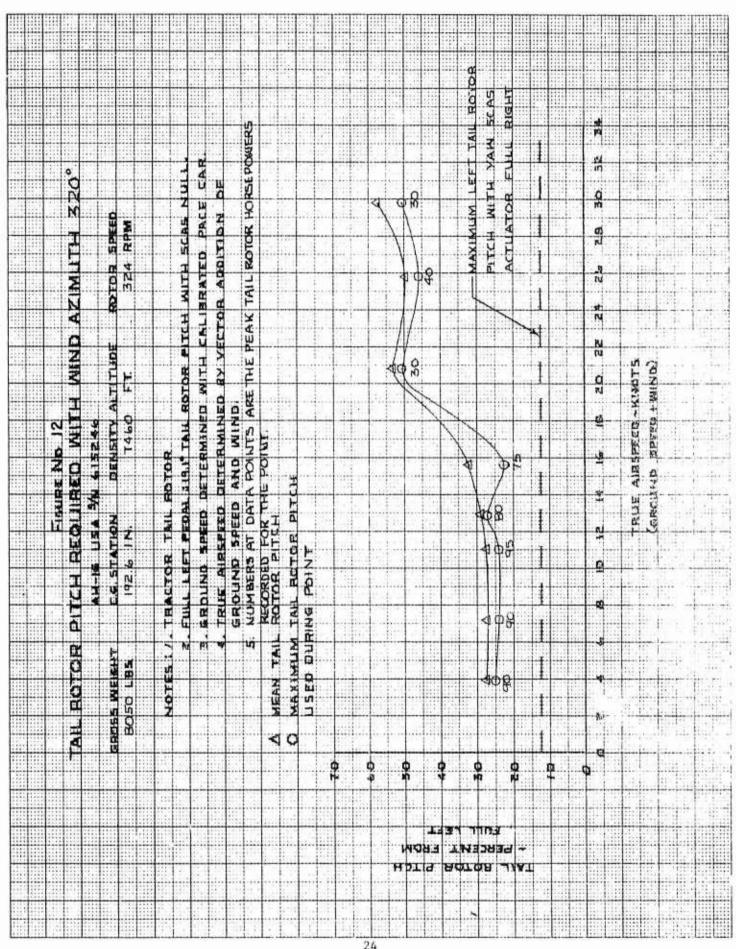


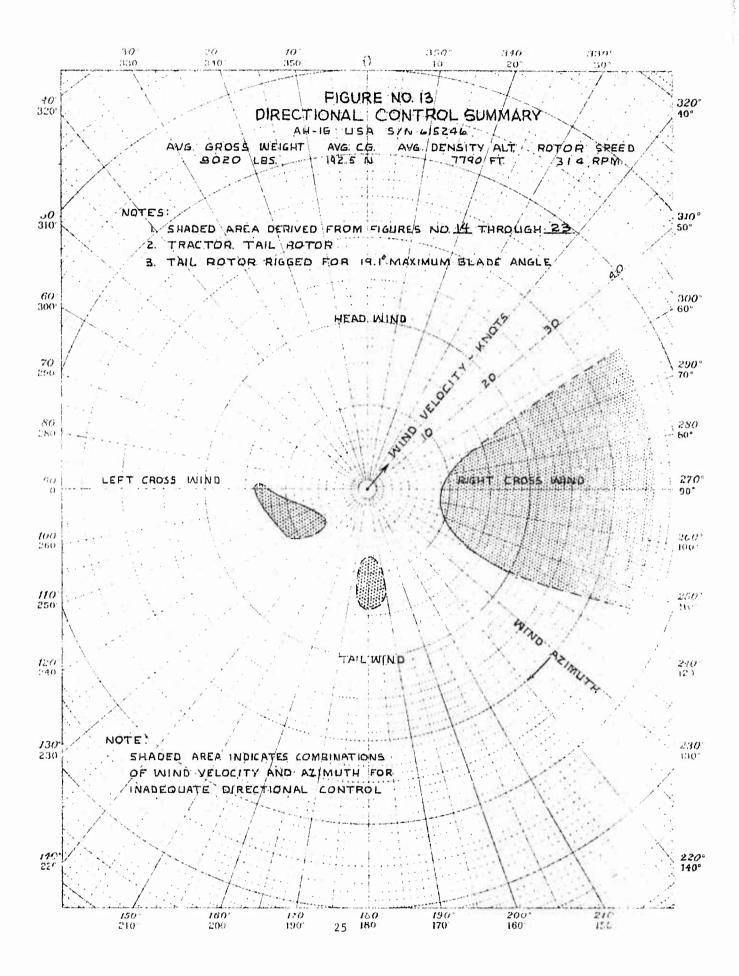


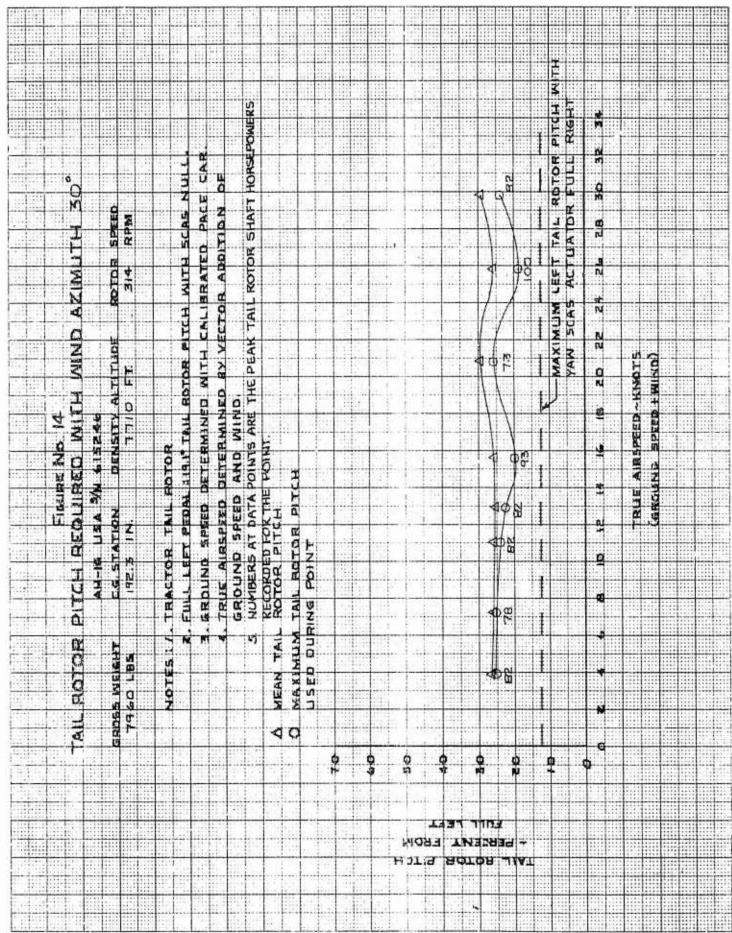


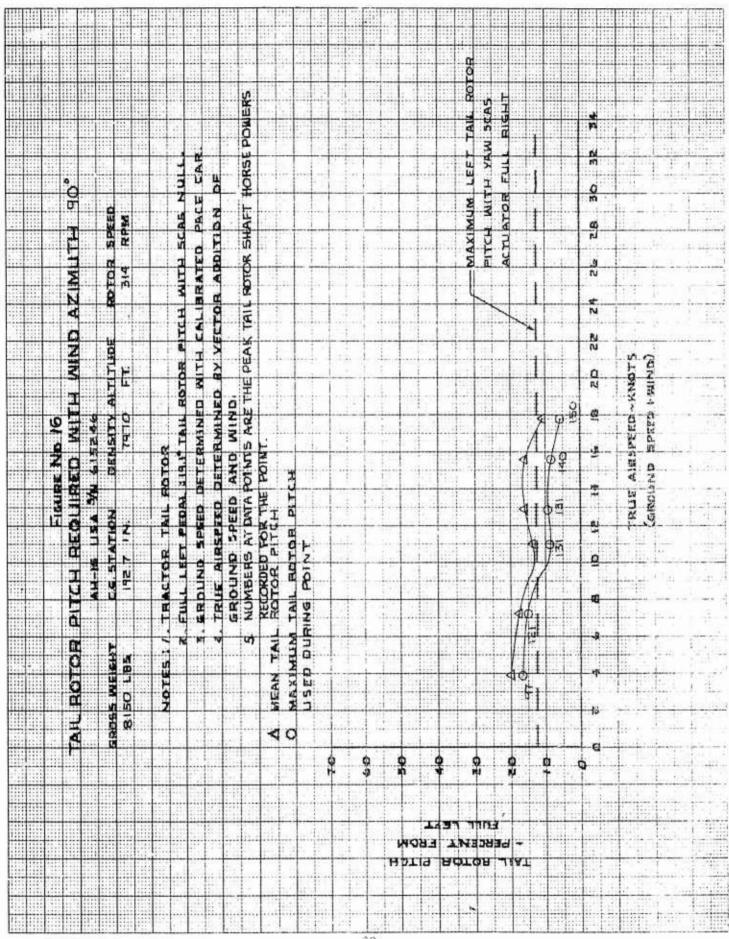


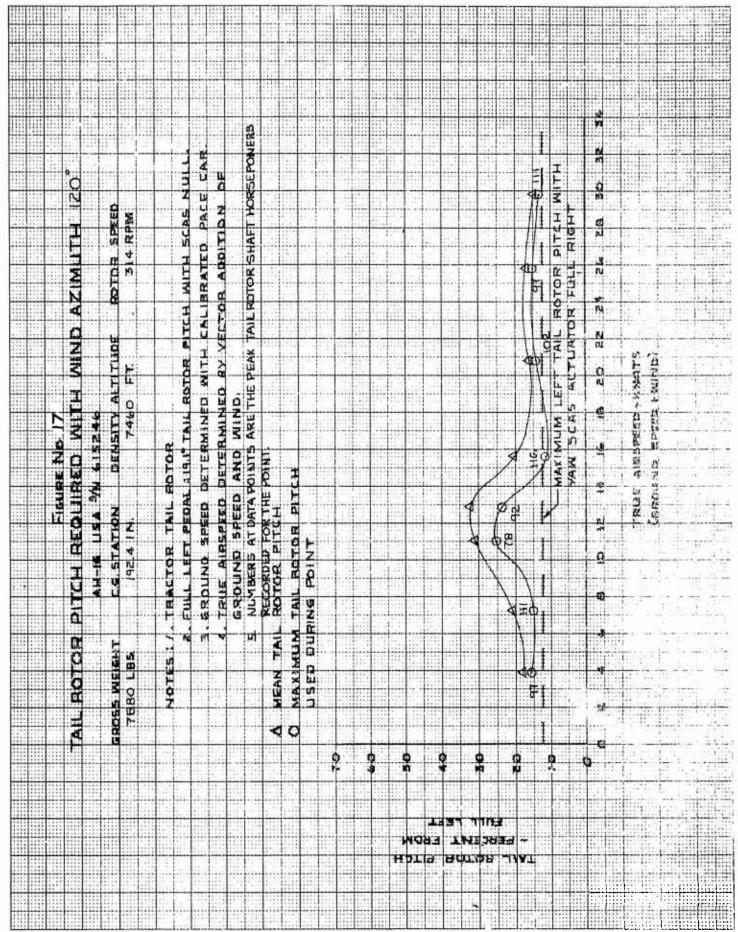


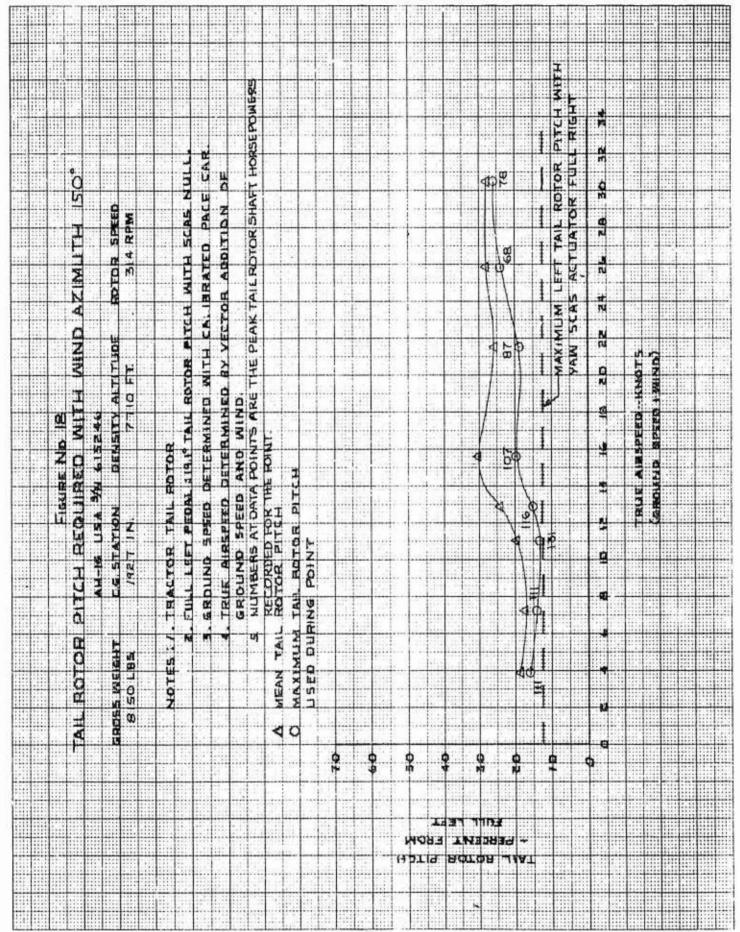






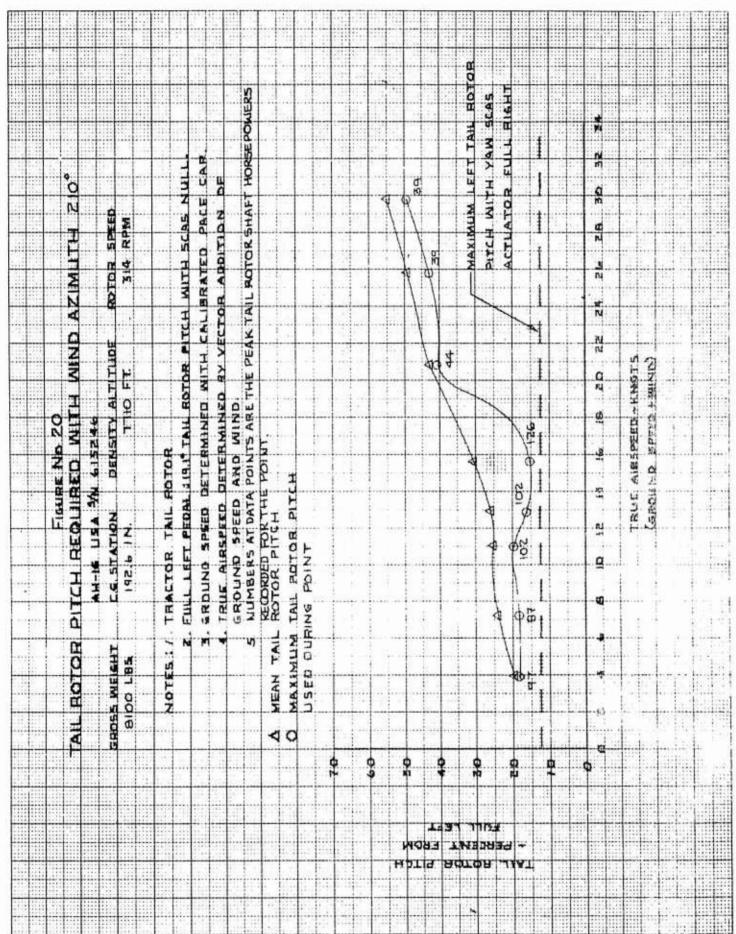


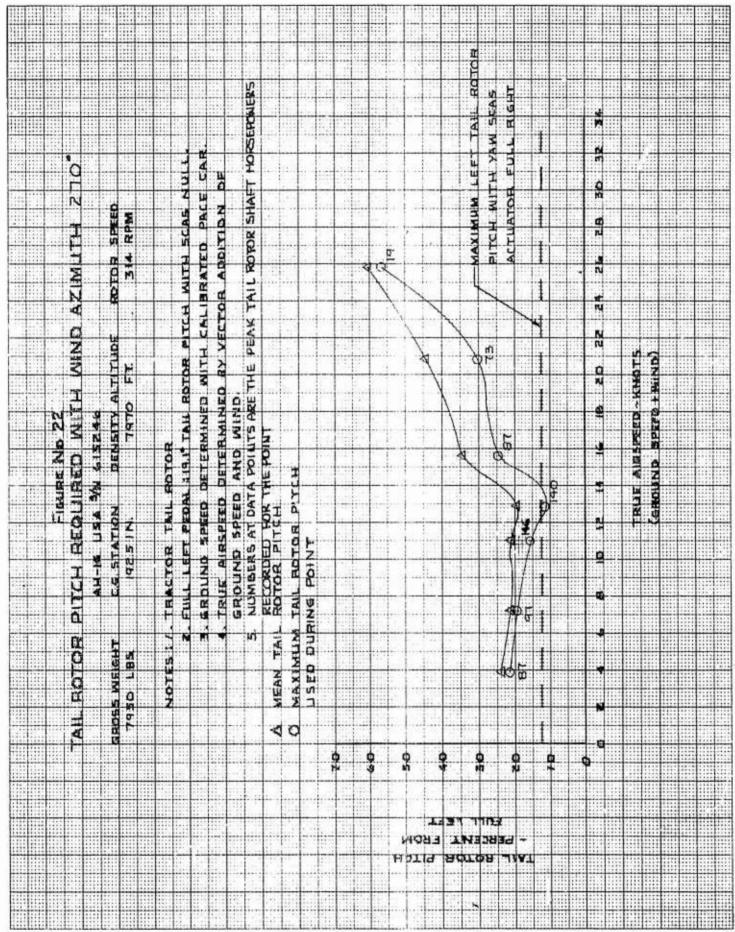


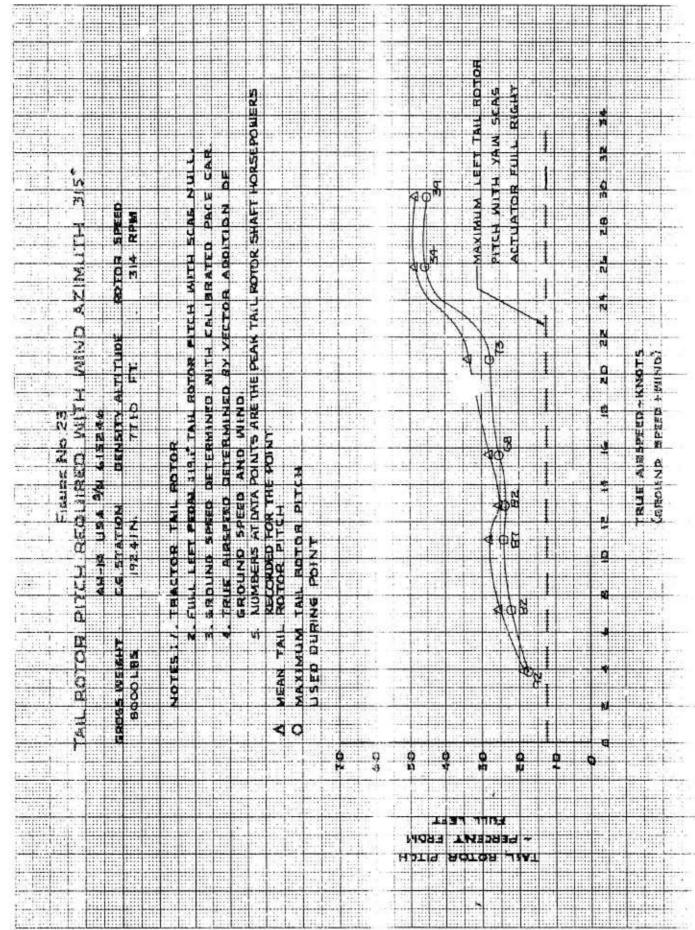


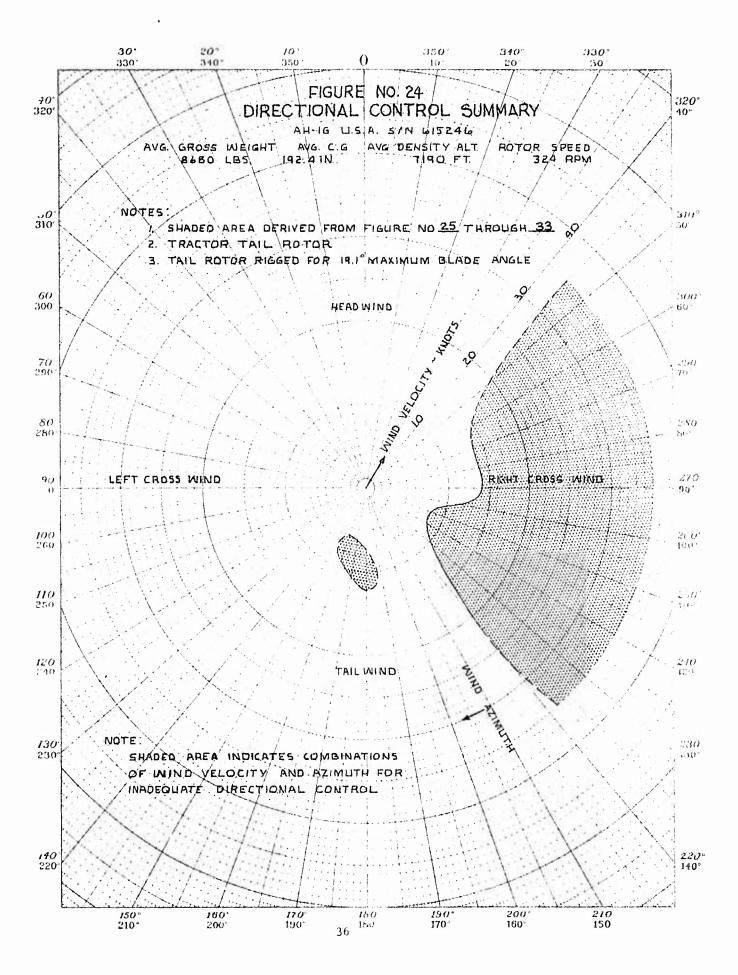
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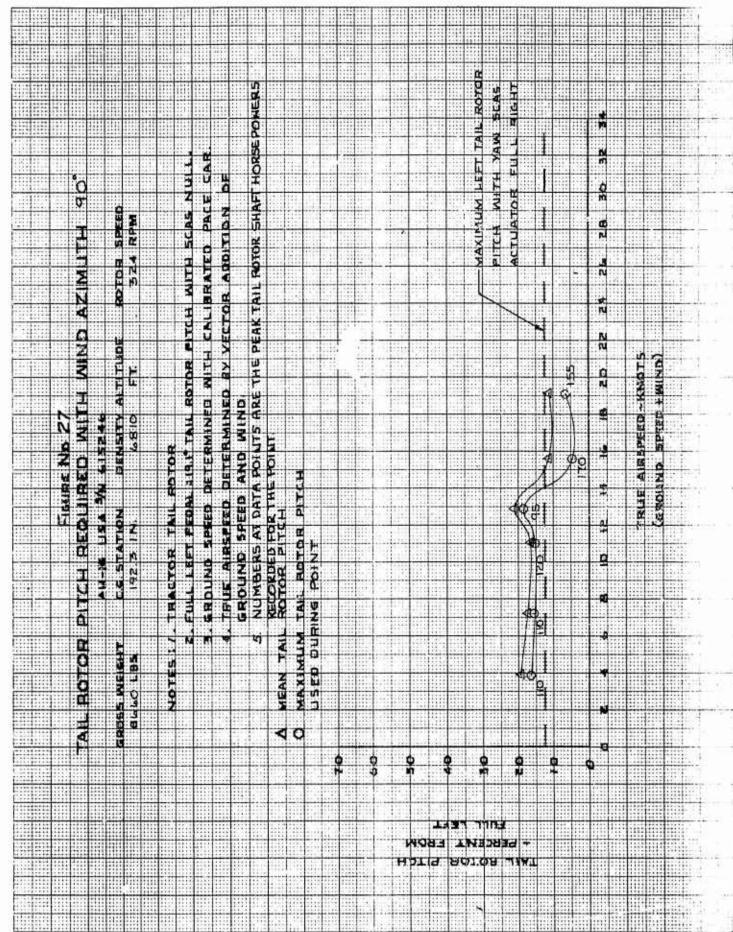


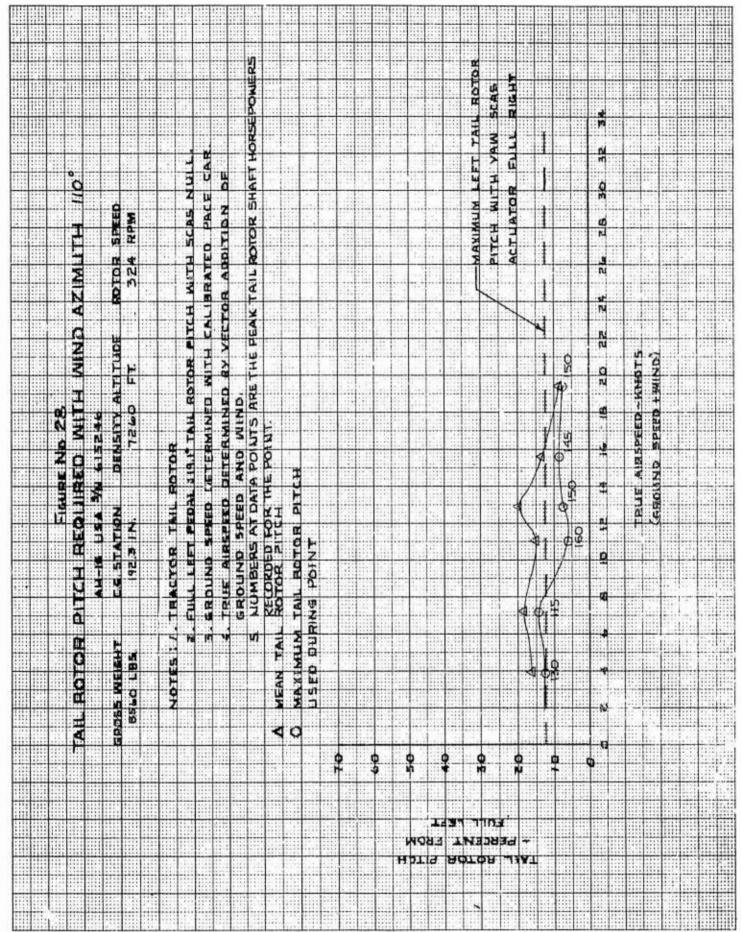




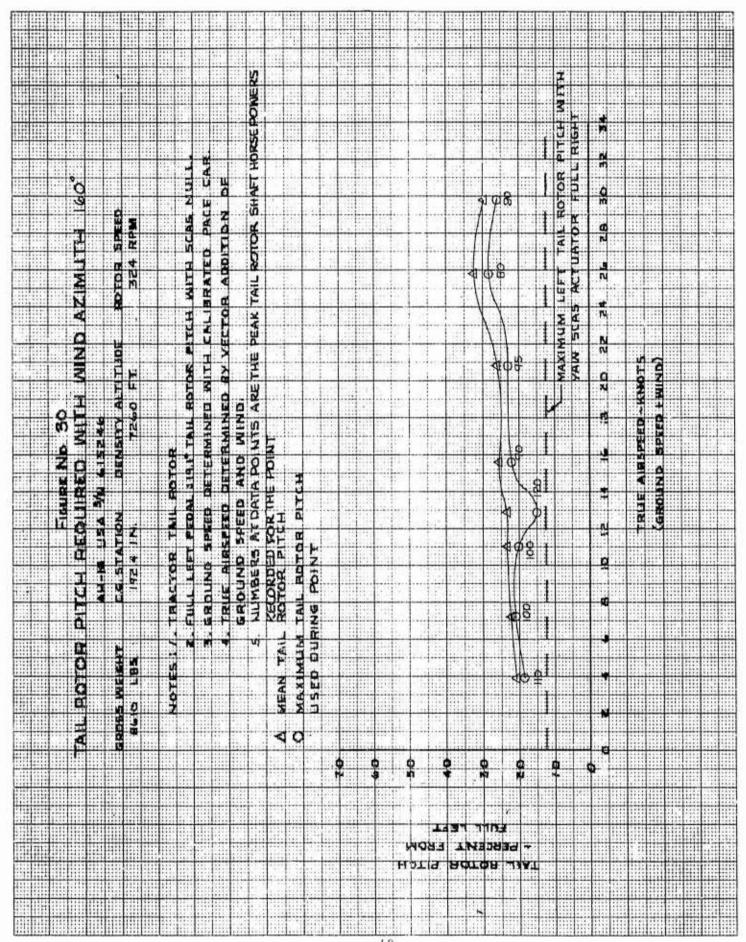
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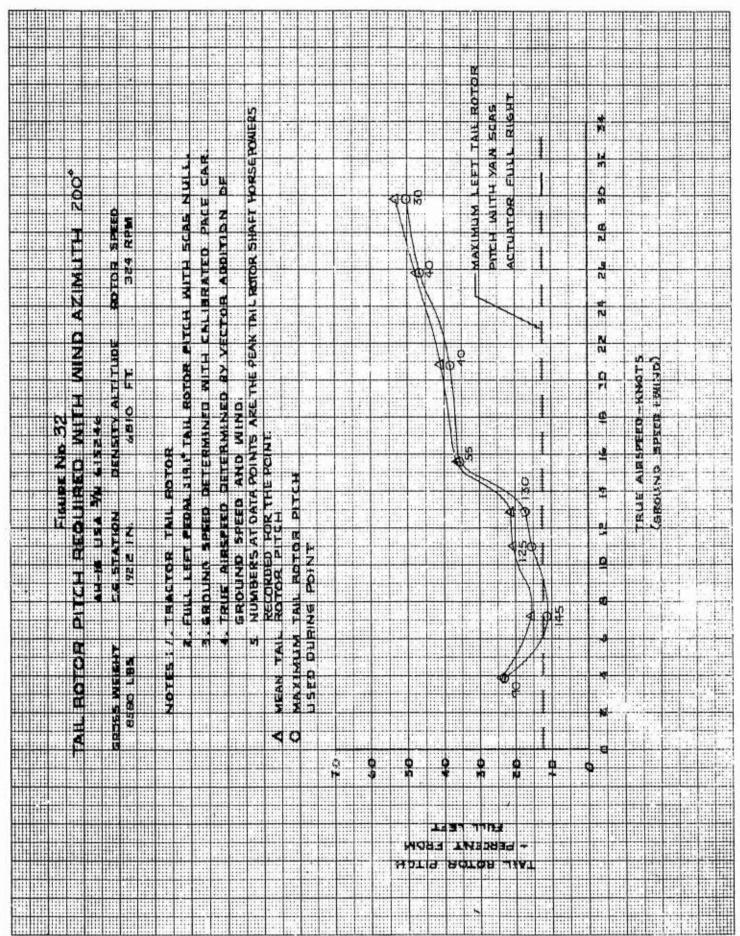
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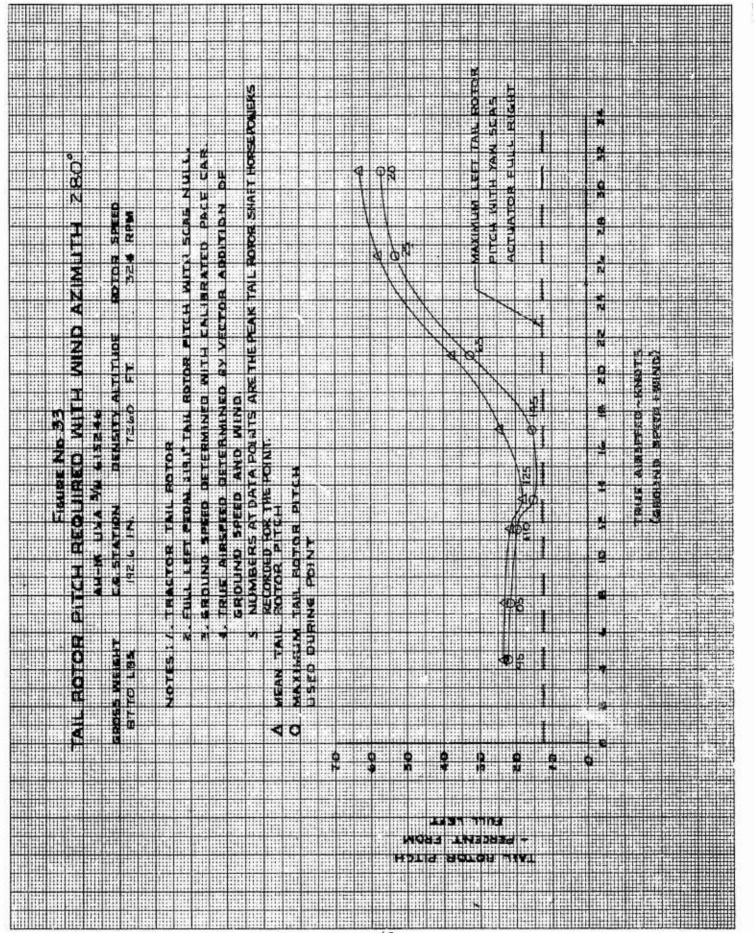


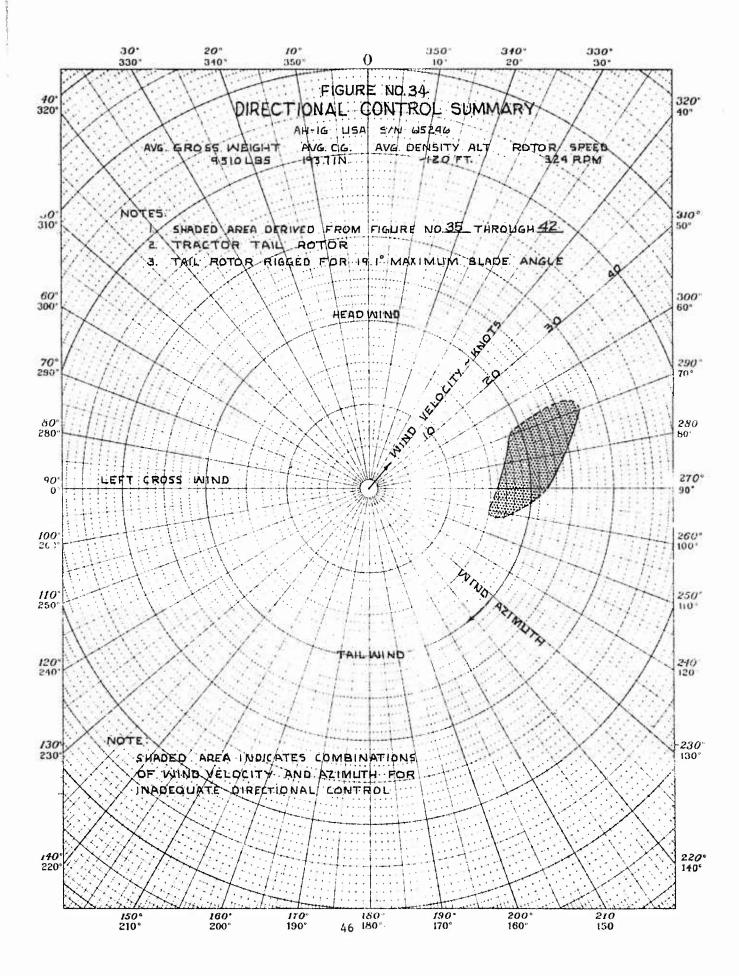


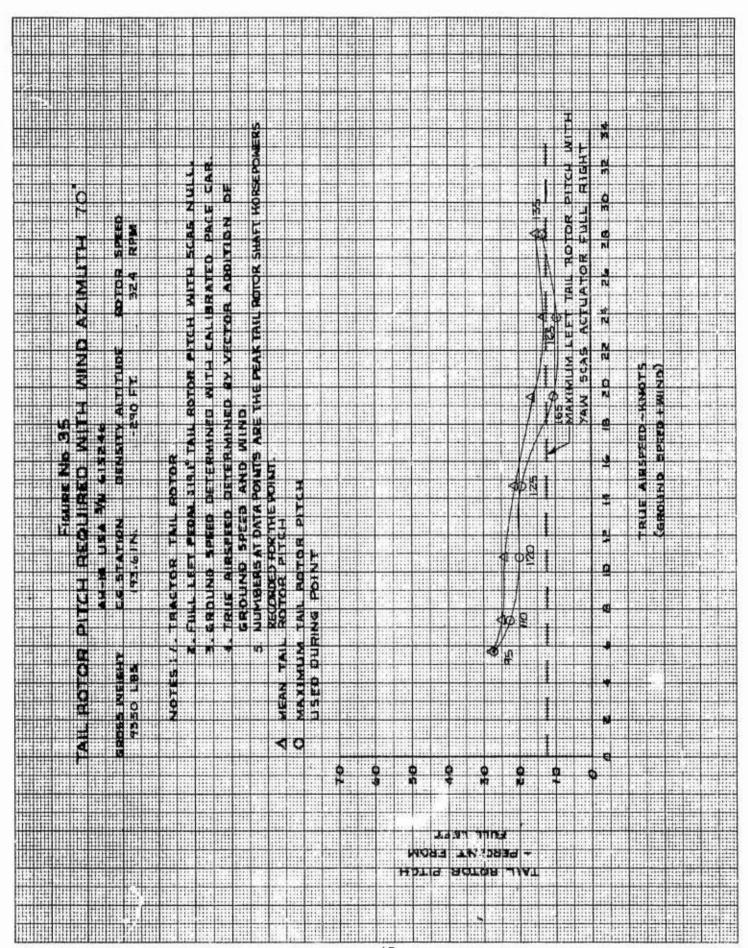
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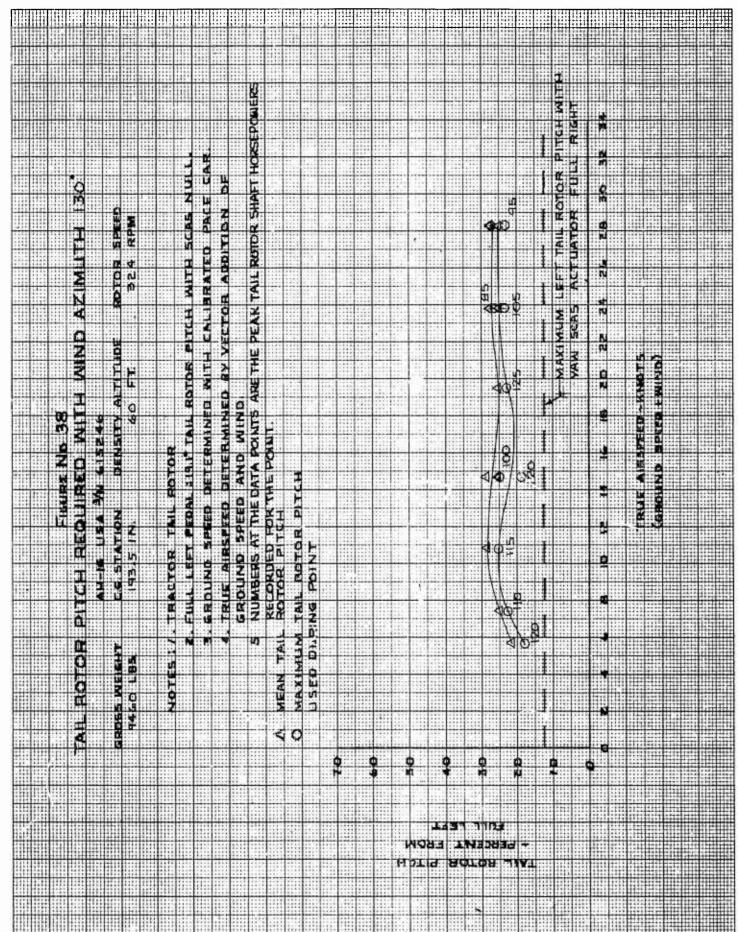


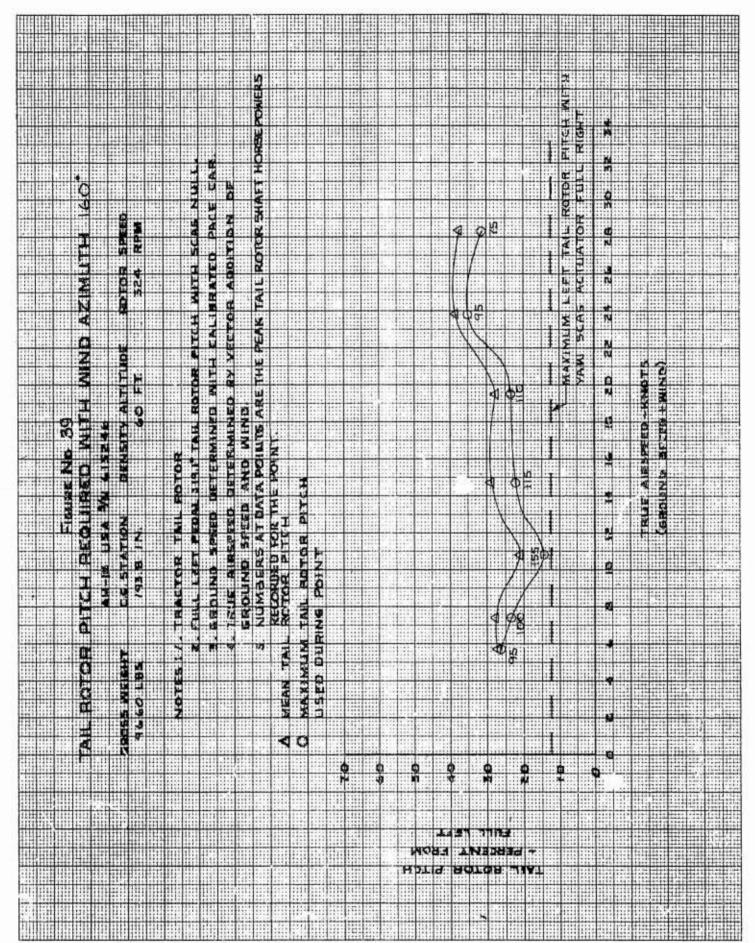


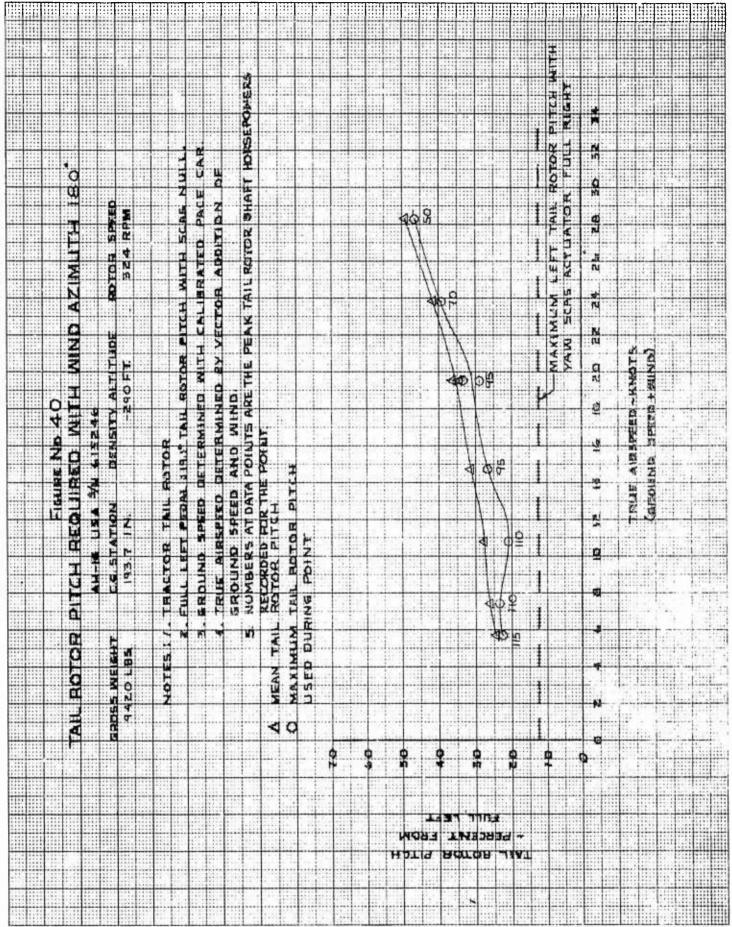


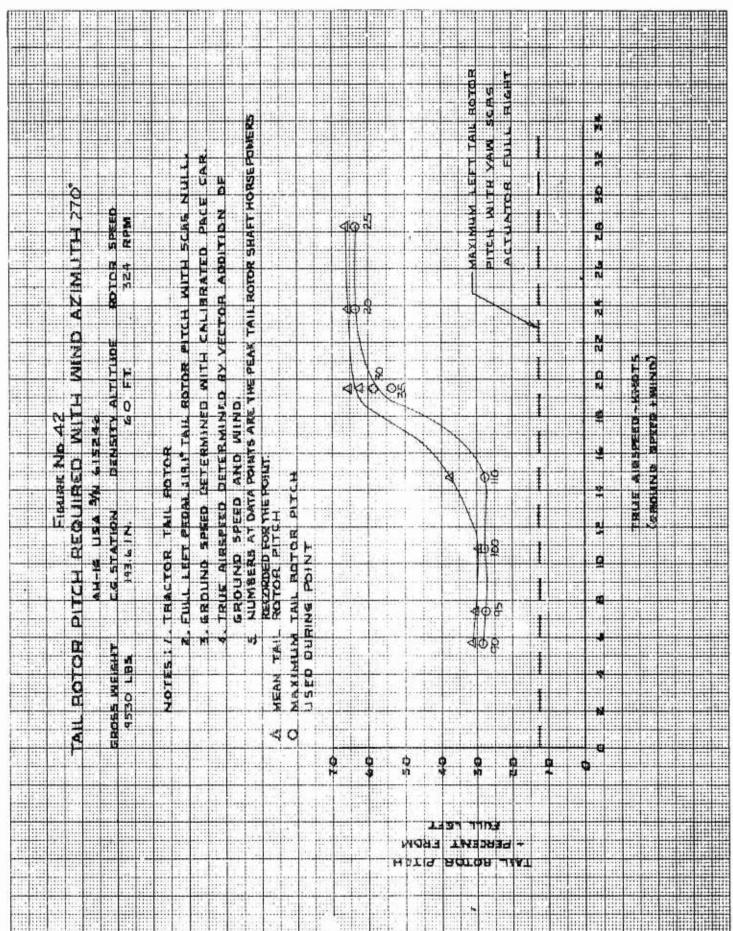


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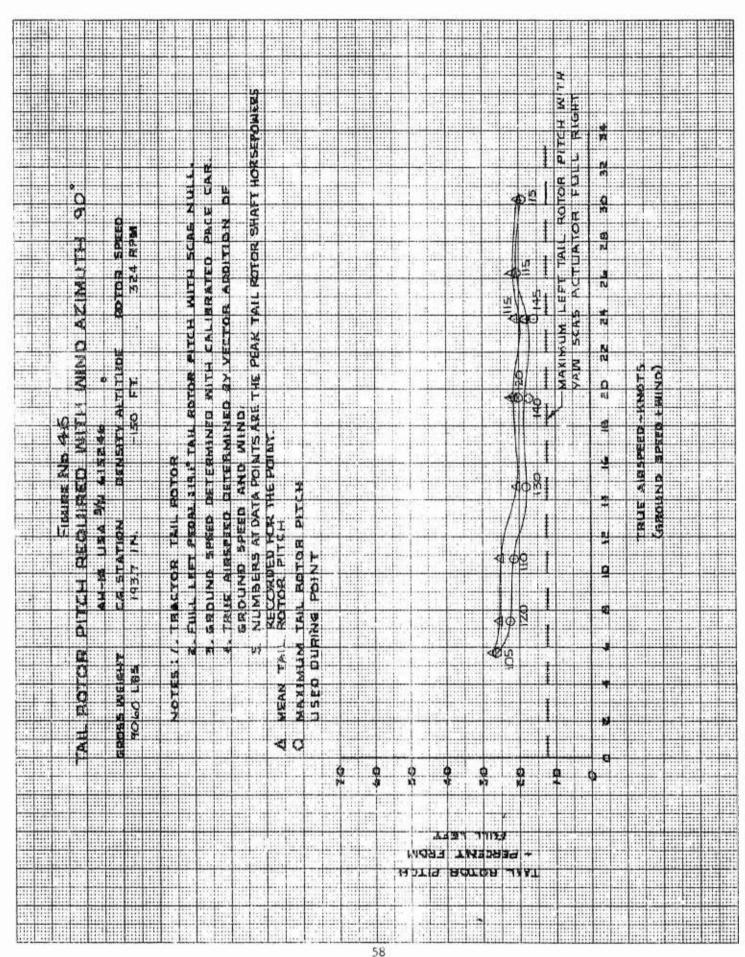






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WAXIMUM LEFT TAL ROTOR PITCH WITH YAM SERS PLEATED FULL RIGHT HORSEPONERS \$ 89 1 NAR. 177 L 9 SCAS N SHAFF PACE TRIE PREFETO DETERMINED BY VECTOR ADDITION SPEED RPM H 3. GROUND SPRED DETERMINED MITH CALIBRATED MUMBERS AT DATA POINTS ARETHE PEAK TAIL ROIDE ROTOR , a Z. FULL LIFET PEDAL SIGN TAIL ROTCH PITCH MITH Z 32 ř Ą O ru ru DENSITY ALTITUDE Z REPERT - KAKOTS t O -REGURED WITH -150 GROUND SPEED AND MIND FIGURE No 45 4.13246 RECORDED FOR THE POINT ROTOR PITCH THACTOR TAIL ROTOR CANDICAL ALREA 4 MAXIMIM TAIL ROTCH PITCH AH-IS USA 3/6 C.G. STATION 2 USED DURING POINT HULLI 193 2 TAIL VOTES: / ROTOR GROSS WEIGHT 8980 LBS NAME 408 AP OF H 40 0 THEREMY



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HOVERING TURN IN WIND AH-1G USA 5/N 615246 FIGURE NO. 48

S. G. GROSS WEIGHT 9130 LBS.

DENSITY ALTITUDE 8760 FT STATION N1 5.561

ROTOR SPEED 324 RPM

NOTES:

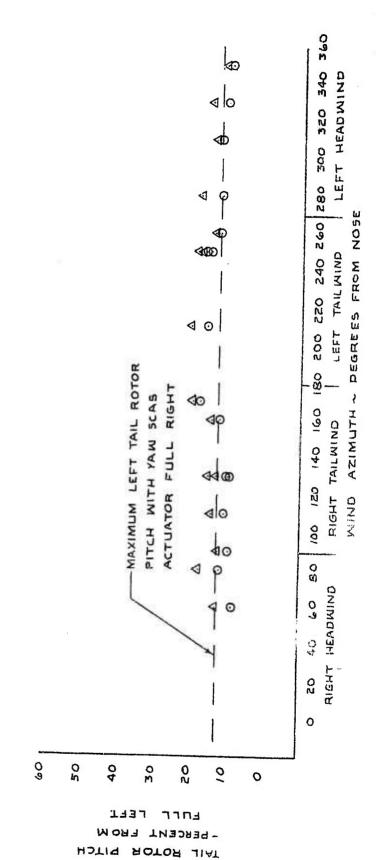
1. WIND GUSTING FROM ZERO TO APPROXIMATELY & KNOTS

Z. TRACTOR TAIL ROTOR

3. FULL LEFT PEDAL = 19.1° TAIL ROTOR PITCH WITH SCAS NULL,

MEAN TAIL ROTOR PITCH

MAXIMUM TAIL ROTOR PITCH USED DURING POINT 40



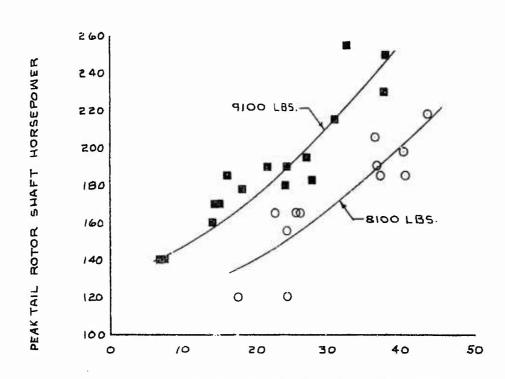
# FIGURE No. 49 TAIL ROTOR SHAFT HORSEPOWER TO ARREST RIGHT HOVERING TURN

AH-16 USA 5/N 615246

5 Y M	GROSS WEIGHT ~ LBS.	C.G. STATION ~IN.	DENSITY ALTITUDE ~ FT.	ROTOR SPEED
	DOIP	192.5	8750	324
0	8100	192.7	7920	324

#### NOTES:

- ! WIND LESS THAN APPROXIMATELY 8 KNOTS.
- 2. PEDAL INPUT COMPLETED IN LESS THAN APPROXIMATELY 1.5 SECONDS.
- 3. TRACTOR TAIL ROTOR
- 4. FULL LEFT PEDAL = 19.1° TAIL ROTOR PITCH WITH SCAS NULL.



SIZE OF PEDAL INPUT TO ARREST TURN -- PERCENT OF FULL TRAVEL

Peak Tail Rotor Shaft Horsepower During Paced Flight AH-1G Helicopter S/N 615246. Table 2.

NOTES:

25.8 20.8 29.8 1. TRAC? OR TAIL ROTOR 2. FULL LEFT PEDAL =  $19.1^{\rm o}$  TAIL ROLOR PITCH WITH SCAS NULL 29.8 25.8 GROSS WEIGHT • DENSITY ALTITUDE • ROTOR SPEED 8030 lbs 7330 ft 324 rom 25.8 20.8 15.6 15.6 15.6 15.6 11.0 =  $\Box$ 3.9 3.9 3.9 3.5 3.9 3.9 PEAK TAIL ROTOR SHAFT HORSEPOWER INSPIED ~ KNOTS RELATIVE WIND VZIMUTH ~ DUCREES

Table 3. Peak Tail Rotor Shaft Horsepower During Paced Flight AH-1G Helicopter S/N 615246.

1.TRACTOR TAIL ROTOR 2.FULL LEFT PEDAL = 19.1° TAIL ROTOR PITCH WITH SCAS NULL GROSS WEIGHT • DENSITY ALTITUDE • ROTOR SPEED 8020 lbs 7790 ft	11 12.9 15.6 20.8 25.8 29.8	82 82 93 73 102 82	7.2 11 12.9 15.6	97 116 102 126	11 12.9 15.6 17.8	131 131 140 150	11 12.9 15.6 20.8 25.8 29.8	78 92 116 107 97 111	11 12.9 15.6 21.5 25.8 30.5	131 116 107 87 68 78	11 12.9 15.6 20.8 25.8	140 160 92 97 87	11 12.9 15.6 20.8 25.8 29.8	102 102 126 44 39 39	11 12.9 15.6 20.8 25.8 29.8	155 58 34 24 15 15	11 12.9 15.6 20.8 25.8	116 140 87 73 19	11 12.9 15.6 20.8 25.8 29.8	87 82 68 73 34 39
NOTES: 1.TRACTOR TAIL ROTOR 2.FULL LEFT PEDAL = GROSS WEIGHT • DEN 8020 lbs 779	3.9 7.2	82 78	3.9 7.2 7	92 107	3.9 7.2	97 121 13	3.9 7.2	97 111	3.9 7.2	AIRSPEED ~ KNOTS 111 111 1.	TAIL ROTOR 3.9 7.2	R 107 116	3.9 7.2	97 87 10	3.9 7.2	102 121 15	3.9 7.2	87 97 11	3.9 7.2 1	92 82 8
RELATIVE WIND	30			70		06		120		150 AIRSPEED	PEAK TAI	180 SHAFT HO		210		240		270		315
_								SES	ECRI	DI	→ H.I	ภหา	ZΑ				<u> </u>			

Table 4. Peak Tail Rotor Shaft Horsepower During Paced Flight AH-1G Helicopter S/N 615246.

NOTES:

1. TRACTOR TAIL ROTOR 2. FULL LEFT PEDAL = 19.1 O TAIL ROTOR PITCH WITH SCAS NULL

		·	0 80	GROSS WEI 8680 lb	WEIGHT • DE lbs 7]	DENSITY AL	• DENSITY ALTITUDE • 7190 ft	RO 32	SPEED	
3.6				8.7	10.2	12	14.6	119	24	28
110	110	110		95	105	110	120	120	110	110
3.4	3.4	3.4		7.2	11	12.9	15.6	19.1	19.8	
105	105	105		11.5	115	120	140	125	165	A.
3.9	3.9	3.9		7.2	11	12.9	15.6	19.1		
110	110	110		110	120	95	170	155		5
3.9	3.9	3.9		7.2	11	12.9	15.6	19.4		
130	130	130		115	160	150	145	150		
AIRSPEED ~ KNOTS 5.5		5.5		10.6	13	15.8	18.5	22.5	29	32
PEAK TAIL ROTOR 115		115		110	145	110	110	145	120	105
SHAFT HORSEPOWER 3.9		3.9		7.2	11	12.9	15.6	20.8	25.8	29.8
110	110	110		100	100	120	06	95	80	80
3.9	3.9	3.9		7.2	11	12.9	15.6	20.8	25.8	29.8
110	110	110		135	150	130	80	85	75	55
3.9	3.9	3.9	_	7.2	11	12.9	15.6	20.8	25.8	29.8
06	<u>6</u>	96		145	125	130	55	40	40	30
4.5	4.	4.	2	7.6	11.6	13.2	17	21	26.4	31
66		96	10	105	110	125	145	65	25	20

Table 5. Peak Tail Rotor Shaft Horsepower During Paced Flight AH-1G Helicopter S/N 615246.

				A	ZIM	UTH	~	DEG:	REE	S							
270		200		180		160		130		110		90	i	,	0.5	RELATIVE WIND	
						SHAFT HORSEPOWER	AIRSPEED ~ KNOTS										NOTES: 1.
90	5.7	95	5.7	115	5.7	95	5.7	120	5.7	110	5.7	120	5.7	95	5.7	GROSS 9510	
95	7.4	120	7.4	110	7.4	100	7.4	110	7.4	115	7.4	135	7.4	110	7.4	GROSS WEIGHT 9510 lbs	1. TRACTOR TAIL ROTOR 2. FULL LEFT PEDAL =
100	10.8	95	10.8	110	10.8	155	10.8	115	10.8	150	10.8	150	10.8	120	10.8	• DENSI -120	ROTOR DAL = 19
110	14.7	70	14.7	95	14.7	115	14.7	120	14.7	165	14.7	155	14.7	125	14.7	ft (TY ALTI)	.1° TAIL
35	19.5	60	19.5	95	19.5	110	19.5	100	14.7	140	19.5	170	19.5	165	19.5	TUDE • RO	ROTOR P
30	19.5	40	19.5	95	19.5	95	23.8	125	19.5	115	19.5	150	19.5			• DENSITY ALTITUDE • ROTOR SPEED -120 ft 324 rpm	TRACTOR TAIL ROTOR FULL LEFT PEDAL = 19.1° TAIL ROTOR PITCH WITH SCAS NULL
.20	23.8	40	23.8	70	23.8			105	23.8	110	23.8	130	23.8	165	23.8	Œ	H SCAS N
25	28.3	40	28.3	50	28.3	75	28.3	95	28.3	120	28.3	140	28.3	135	28.3		מדז.
								85	23.8								
								105	28.3								

Table 6. Peak Tail Rotor Shaft Horsepower During Paced Flight AH-1G Helicopter S/N 615246.

NOTES: 1.TRACTOR TAIL ROTOR
2.FULL LEFT PEDAL = 19.1° TAIL ROTOR PITCH WITH SCAS NULL GROSS WEIGHT • DENSITY ALTITUDE • ROTOR SPEED 8940 lbs -150 ft 324 rpm

	ΑZ	IMU	TH ~	v D	EĞR	EES		72
TTU		90	3	ò	3	Ü	n O	RELATIVE WIND
			SHAFT HORSEPOWER	DEAK TATI ROTOR	ATREPERD A KNOTS			E
100	10.7	105	5.7	90	1.7	100	11.7	8940 lbs
95	11.4	120	7.4	100	3.4	110	11.9	8940 lbs
105	13.8	110	10.8	110	6.8	115	14.8	
95	18.7	130	14.7	110	10.7	135	18.7	ft ft
160	23.5	120	19.5	160	15.5	155	23	32
95	16.5	140	19.5	145	19.8	110	16	-150 ft 324 rpm
105	19.8	145	23.8	130	28.8	125	20.8	
115	27.8			135	32.8	145	24.8	
110	32.3	115	26.3					
		115	30.3					

# APPENDIX III TEST INSTRUMENTATION

1. Flight test instrumentation was installed in the test helicopter by the contractor prior to the start of this evaluation. Although other test instrumentation was installed in the test aircraft only those items on the oscillograph used in data collection for this test will be specified below. All instrumentation was calibrated by the contractor and witnessed or approved by the USAAVNTA flight test engineer. The flight test instrumentation was maintained by the contractor throughout the test program. The following parameters were utilized during this test:

#### Oscillograph:

All flight control positions
Tail rotor pitch (acme thread)
Yaw attitude
Tail rotor shaft torque
SCAS actuator positions
Engine torque
Rotor speed

2. Additional items installed in the test aircraft specifically required for this test were:

#### Pilot's Panel:

Altimeter
Outside air temperature gage
Directional control position indicator
Calibrated directional gyro
Calibrated compass
Tail rotor torque gage
VHF radio

### APPENDIX IV

# AH-IG OPERATING LIMITATIONS

- 1. Limit airspeed  $(V_{\tau})$ :
  - Power on 120 KIAS for all configurations and gross weights up to 9500 lbs at density altitude up to 3000 feet. For all configurations, reduce airspeed 8 KIAS per 1000 feet above 3000 feet.

Power off - 120 KIAS.

- 2. Gross weight Center of Gravity Envelope:
  - Forward limit: Below 7000 lb, Fuselage Station (F.S.) 190. Linear decrease from F.S. 190 at 7000 lb to F.S. 192.1 at 95000 lb.
  - Aft limit: Below 7650 lb, F.S. 201. Linear decrease from F.S. 201 at 7650 lb to F.S. 200 at 9500 lb.
- Sideslip limits: 5 degrees at 190 KCAS. Linear increase to 20 degrees at 60 KCAS.
- 4. Maximum load factor:
- 5. Sideward and rearward flight: 35 kt
- 6. Maximum turn rate: 40 degrees per second
- 7. Maximum tail rotor horsepower, interim value proposed by contractor: 200 hp (inspection required)
- 8. RPM limits (steady state):
  - Power on 6600 to 6400 engine rpm 324 to 314 rotor rpm
  - Power off 304 to 339 rotor rpm transient lower limit 250 rotor rpm

Power on during dives and maneuvers 319 to 324 rpm

9. Temperature and pressure limits:

Engine oil temperature

Transmission oil temperature

Engine oil pressure

Transmission oil pressure

Transmission oil pressure

Fuel pressure 30 - 70 psiFuel pressure 5 - 20 psi

10. T53L-13 Engine limits - installed:

Normal rated power (maximum continuous)

Military rated power (30-minute limit)

Starting and acceleration

(5-second limit)

Maximum for starting and acceleration

Torque pressure

625°C Exhaust gas temperature (EGT)

645°C EGT

675°C EGT

760°C EGT

50 psi

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FEASIBILITY TEST OF THE TRACTOR	TAIL ROTOR MODIFICATION	ON ON THE A	AH-IG HELICOPIER
4. DESCRIPTIVE NOTES (Type of report and inclusion	ive dates)		
Final Report - 7 October throug	gh 31 October 1967		
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John R. Melton, Project Enginee	er		
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11. SUPPLEMENTARY NOTES	12. SPONSORING	MILITARY ACT	TIVITY

13. ABSTRACT

N/A

A feasibility test of the tractor tail rotor modification of the AH-1G helicopter was conducted near Fort Worth, Texas (550-feet elevation), and Alamosa, Colorado (7535feet elevation), during the period 7 October to 19 October 1967. This test was conducted to obtain quantitative flight test data to serve as a basis for determining if the tractor tail rotor modification proposed by the contractor for the AH-1G helicopter would correct the directional control problems which currently exist on the AH-1G helicopter with the standard tail rotor configuration. This test revealed that inground-effect (IGE) low speed directional control and IGE low speed dynamic directional stability were greatly improved by installation of the tractor tail rotor. IGE directional control limitations with the standard tail rotor installed were encountered at approximately 8100 pounds gross weight near sea level in previous tests. This test with the tractor tail rotor did not reveal any IGE directional control limitations at approximately 8940 pounds gross weight and near sea level. The test results indicate that additional directional control could be obtained with the tractor tail rotor, if the geometry of the directional control system were changed to negate the adverse effects of the stability and control augmentation system (SCAS) on the ability to obtain full left tail rotor pitch. The highest tail rotor horsepower encountered with large left pedal inputs to arrest hovering turns was 250 shaft horsepower. These tests proved that directional control deteriorated with increased gross weight, increased density altitude or decreased rotor speed. The test aircraft exhibited SCAS coupled pylon motion which has been a continuing problem on the AH-1G helicopter.

Commanding General

US Army Aviation Materiel Command

St. Louis, Missouri 63166

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14. KEY WORDS	LINK A		LINK B		LINKC	
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AH-1G helicopter	İ					
Tractor tail rotor modification	4					
In-ground-effect	i					
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